

Enabler Release Definition for Dynamic Navigation (DynNav) Candidate Version 1.1 – 02 Sep 2014

Open Mobile Alliance OMA-ERELD-DynNav-V1_1-20140902-C

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1. Scope

The scope of this document is limited to the Enabler Release Definition of DynNav Enabler 1.1 according to OMA Release process and the Enabler Release specification baseline listed in section 5.

2. References

2.1 Normative References

[ISO TTI] "Traffic and Travel Information (TTI)" ISO/TS 24530,

URL:http://www.iso.org/iso/iso catalogue/catalogue tc/catalogue tc browse.htm?commid=54706

[RFC2119] "Key words for use in RFCs to Indicate Requirement Levels", S. Bradner, March 1997,

URL:http://www.ietf.org/rfc/rfc2119.txt

 $[\textbf{SCRRULES}] \hspace{1cm} \text{``SCR Rules and Procedures''}, Open \ Mobile \ Alliance \ ^{TM}, OMA-ORG-SCR_Rules_and_Procedures,$

URL:http://www.openmobilealliance.org/

2.2 Informative References

3. Terminology and Conventions

3.1 Conventions

The key words "MUST", "MUST NOT", "REQUIRED", "SHALL", "SHALL NOT", "SHOULD", "SHOULD NOT", "RECOMMENDED", "MAY", and "OPTIONAL" in this document are to be interpreted as described in [RFC2119].

All sections and appendixes, except "Scope", "Release Version Overview" and "Conformance Requirements Notation Details", are normative, unless they are explicitly indicated to be informative.

3.2 Definitions

DynNav Client An entity that is in charge of interacting with a DynNav Server to get optimal route(s) or real-time and

predicted traffic information and complimentary data.

DynNav Server An entity that is in charge of providing to the application optimal route(s), real-time and forecasted traffic

information, and complimentary data.

Enabler Release Collection of specifications that combined together form an enabler for a service area, e.g. a download

enabler, a browsing enabler, a messaging enabler, a location enabler, etc. The specifications that are

forming an enabler should combined fulfil a number of related market requirements.

Minimum Functionality

Description

Description of the guaranteed features and functionality that will be enabled by implementing the

minimum mandatory part of the Enabler Release.

Navigation Device An entity that, using GNSS service, assists the driver showing correct route to reach the final destination.

This entity may process real-time and predicted traffic information and dynamically estimates the optimal

route, according to user preferences.

Network Performance

Parameter

Information regarding the performances (i.e. speed, delay and travel time) of road segments related to an

area or a route.

Point Of Interest POI describes information about locations such as name, category, unique identifier, or civic address.

Route Information Information which coordinates of segment end points and complimentary data from the defined origin and

the destination

Traffic Information Information which consists of traffic events and network performance parameters related to an area or a

route

3.3 Abbreviations

API Application Programming Interface

ND Navigation Device

OMA Open Mobile Alliance

POI Point Of Interest

REST REpresentational State Transfer

SCR Static Conformance Requirements

TPEG Transport Protocol Expert Group

TS Technical Specification
URL Uniform Resource Locator
XML eXtensible Markup Language
XSD XML Schema Definition

4. Release Version Overview

The DynNav Enabler provides an overall framework (mechanisms, functionalities, APIs, and etc.) to enable dynamic routing of vehicle based on traffic information.

The following areas will be covered as part of the scope of the enabler:

- Delivering traffic information and/or route information to the Navigation Device (ND);
- Delivering value added information to the ND, such as Point Of Interest (POI);

DynNav Enabler will reuse as much as possible existing technologies. In particular, with respect to interface specification, it is in the scope of this Enabler:

• to reuse traffic information data formats defined by TPEG in [ISO TTI],

4.1 Version 1.0 Functionality

The version 1.0 of the DynNav Enabler defines an overall framework that enables dynamic vehicles navigation service based on traffic information over a mobile network.

The core functionalities exposed by the DynNav Enabler include the following operations:

- Request and Provide a set of routes based on the journey parameters defined by the user
- Provide traffic information related to the route and an area defined by the ND
- Provide complementary information(i.e. POI) related to defined routes and/or areas
- Manage subscriptions to notification services for updates on traffic information and alternative route proposal

4.2 Version 1.1 Functionality

DynNav 1.1 supports the following functionalities additional to those in Version 1.0.

- Additional journey definition such as recurrent routes including time conditions and routes to the 3rd party for Smart ND
- Journey and route information sharing with interested 3rd parties through public resources
- Request and provide the optimal route to visit multiple waypoints complying with time and priority constraints
- Provide the list of POIs accessible within a defined travelling time/distance, and additionally related route information to the selected POI
- Supporting the common traffic information for reuse as opposed to the user-specific traffic information

5. Document Listing for DynNav 1.1

This section is normative.

Doc Ref	Permanent Document Reference	Description				
Requirement Document						
[DynNav ER] OMA-ER-DynNav-V1_1-20140902-C		Requirements and Architecture Document for DynNav 1.1 Enabler				
Architecture Document						
		None will be defined.				
Technical Specification						
[DynNav TS] OMA-TS-REST_NetAPI_DynNav-V1_1- 20140902-C		Technical Specification for DynNav 1.1 Enabler				
Supporting File						
[REST_SUP_DYNNAV]	OMA-SUP-XSD_rest_DynNav-V1_1-20140902-C	XSD schema for XML data structure definition				

Table 1: Listing of Documents in DynNav Enabler

6. OMNA Considerations

The REST_NetAPI_DynNav enabler introduces the following namespaces.

Note that in order to maintain compatibility between minor versions of the same major version, only the major version is reflected in the namespace identifier. Further note that subsequent minor versions of the same XML schema (e.g. 1.1) will be registered against the same namespace identifier.

Description	Registered URN	Schema Links
Dynamic Navigation	urn:oma:xml:rest:netapi:dynnav:1	http://www.openmobilealliance.org/tech/profiles/rest_netapi_dynnav-v1_1.xsd

Table 2: OMNA Namespaces

7. Conformance Requirements Notation Details

This section is informative.

The tables in following chapters use the following notation:

Item: Entry in this column MUST be a valid ScrItem according to [SCRRULES].

Feature/Application: Entry in this column SHOULD be a short descriptive label to the **Item** in question.

Requirement: Expression in the column MUST be a valid TerminalExpression according to [SCRRULES] and it

MUST accurately reflect the architectural requirement of the Item in question.

8. ERDEF for DynNav 1.1 - Client Requirements

Not Applicable in RESTfull NetAPI interface definition

9. ERDEF for DynNav 1.1 - Server Requirements

Static Conformance Requirements for a Navigation Server are specified in Appendix B.2 of [DynNav TS].

Appendix A. Change History

(Informative)

A.1 Approved Version History

Reference	Date	Description
n/a	n/a	No prior version

A.2 Draft/Candidate Version 1.1 History

Document Identifier	Date	Sections	Description
Draft Versions	28 Apr 2014	1-5	First draft
OMA-ERELD-DynNav-V1_1	08 May 2014	n/a	Editorial clean up before uploading
	12 May 2014	5	Update the document list prior to Consistency Review
	30 Jun 2014	6	Update the document according to the Consistency Review comment
	22 Aug 2014	5	Editorial update of permanent document references in section 5
Candidate Version	02 Sep 2014	All	Status changed to Candidate by TP
OMA-ERELD-DynNav-V1_1			TP Ref # OMA-TP-2014-0191-
			INP_DynNav_V1_1_ERP_and_ETR_for_Candidate_Approval